



SARL

Agent-Oriented Programming Language

www.sarl.io

Sebastian Rodriguez
(On behalf of SARL Team)

Seminar at Universidade Federal de Santa Catarina – Florianopolis
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srodriguez@gitia.org

Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works

1 GITIA - UTN

2 SARL Team

3 Motivation

4 Design Principles

5 Main Concepts

- Definitions
- Built-in Capacities
- Environment

6 Show me the Code!

7 Summary & Future works



Our University

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SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works

Universidad Tecnológica Nacional

- 29 Faculties - 75 Degrees (16 Engineering Degrees)
- 75.000 students (2008)
- <http://www.utn.edu.ar>

Grupo de Investigación en Tecnologías Informáticas Avanzadas (GITIA)

- Team 15 people
- Master in Information Systems Engineering - FRT - UTN

S. Rodríguez

SARL: Agent Programming Language



GITIA Research Areas

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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Agent Oriented Software Engineering

- MAS Meta-models
- Agent Oriented Software Processes
- MAS Development Platforms and Languages
- CASE for MAS

Optimization

- Artificial Neuronal Networks
- Genetic Algorithms
- Genetic Programming



Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

1 GITIA - UTN

2 SARL Team

3 Motivation

4 Design Principles

5 Main Concepts

- Definitions
- Built-in Capacities
- Environment

6 Show me the Code!

7 Summary & Future works



A whole team

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SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

Design & Development

- Nicolas GAUD
- Stéphane GALLAND
- Sebastian RODRIGUEZ

Contributions and Ideas (a lot !!)

- Olivier BOISSIER
- Vincent HILAIRE
- Flavien BALBO
- Gauthier PICARD
- Luk KNAPPEN
- Many others, every contributor is welcome 😊



Contributions and uses during the Young Age

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works



Energy management & simulation



Energy, Transport & LUTI simulation



Environment definition & transport simulation



Transport management & simulation



Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

1 GITIA - UTN

2 SARL Team

3 Motivation

4 Design Principles

5 Main Concepts

- Definitions
- Built-in Capacities
- Environment

6 Show me the Code!

7 Summary & Future works



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SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

Janus Experience

- Janus code base is almost 10 years old.
- Learned a lot of the DO's and DON'Ts.
- **API became complex** and difficult to maintain.
- Constant need to **refactor to include new features**.
- New patterns have changed software development (IoC, Event-Driven Communication, Distributed Objects, etc.).



Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

1 GITIA - UTN

2 SARL Team

3 Motivation

4 **Design Principles**

5 Main Concepts

- Definitions
- Built-in Capacities
- Environment

6 Show me the Code!

7 Summary & Future works



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SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

Design Principles

- **Clear separation between Language and Platform related aspects.**
- Everything is distributed and it should be transparent.
- Massively parallel.
- Event-driven interactions.
- All agents are holonic.
- Platform- and architecture-independent.
- There is not only one way of interacting but infinite.
- Coding should be fun (Ruby/Scala-like) 😊.



Expectations for SARL

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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Summary & Future works

Expectations for SARL

- Stop implementing **Agents** with **Object**-Oriented concepts.
- Playground to find minimal Agent-Oriented Programming concepts.
- Agents should be simple to extend.
- **Provide the community a common discussion forum.** (a testbed)



Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

- 1 GITIA - UTN
- 2 SARL Team
- 3 Motivation
- 4 Design Principles
- 5 **Main Concepts**
 - Definitions
 - Built-in Capacities
 - Environment
- 6 Show me the Code!
- 7 Summary & Future works



Multiagent system in SARL

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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Code!

Summary &
Future works

a MAS in SARL

A collection of Agents interacting together in a collection of shared distributed Spaces.



Overview of SARL Concepts

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Motivation

Design Principles

Main Concepts

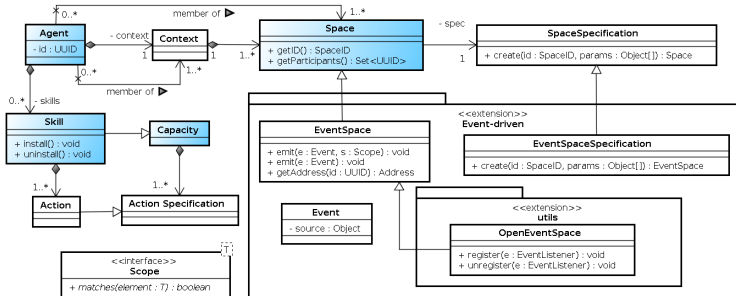
Definitions

Built-in Capacities

Environment

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4 main concepts

- Agent
- Capacity
- Skill
- Space

3 main dimensions

- Individual**: the Agent abstraction (Agent, Capacity, Skill)
- Collective**: the Interaction abstraction (Space, Event, etc.)
- Hierarchical**: the Holon abstraction (Context)



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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

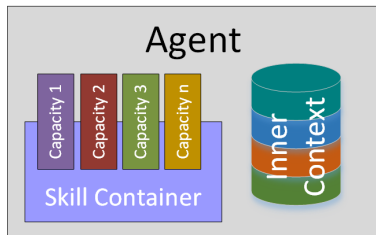
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Agent

- An agent is an autonomous entity having some intrinsic skills to implement the **capacities** it exhibits.
- An agent defines a **Context**.
- An agent initially owns native capacities called **Built-in Capacities**.



Capacities and Skill

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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Summary & Future works

Capacity

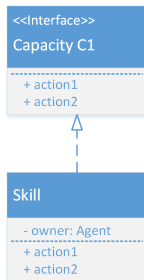
Specification of a collection of actions.

Action

- A specification of a transformation of a part of the designed system or its environment.
- Guarantees resulting properties if the system before the transformation satisfies a set of constraints.
- Defined in terms of pre- and post-conditions.

Skill

A possible implementation of a capacity fulfilling all the constraints of its specification.



Context and Interactions

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

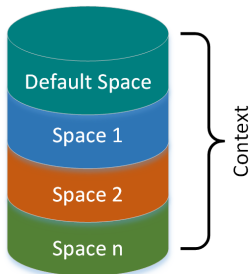
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Context

- Defines the boundary of a sub-system.
- Collection of Spaces.
- Every Context has a **Default Space**.
- Every Agent has a **Default Context**, the context where it was spawned.



Space

Support of interaction between agents respecting the rules defined in various Space Specifications.



Context and Interactions (cont.)

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

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Space Specification

- Defines the rules (including action and perception) for interacting within a given set of Spaces respecting this specification.
- Defines the way agents are addressed and perceived by other agents in the same space.
- A way for implementing new interaction means.

Use case for organizational approach

Space Specification Organization

Space Group

Agent interface Behavior, Role

Addressing Role Address



Context and Interactions (cont.)

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

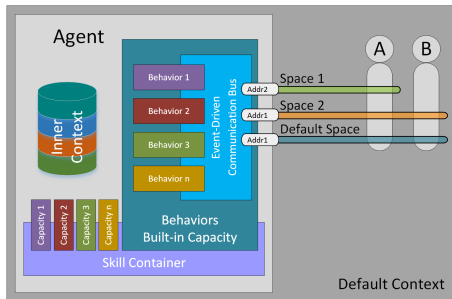
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Default Space: an Event Space

- Event-driven interaction space.
- Default Space of a context, contains all agents of the considered context.
- Event: the specification of some **occurrence** in a Space that may potentially trigger effects by a participant.



Spaces and Contexts

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

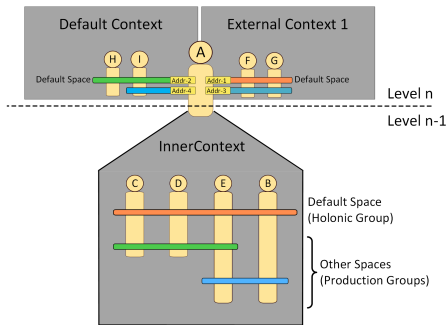
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Contexts and Holonic properties

- All agents have at least one External Context (the default one).
- All agents participate in the Default Space of all Contexts they belong to.
- The Janus Context is omnipresent.



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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

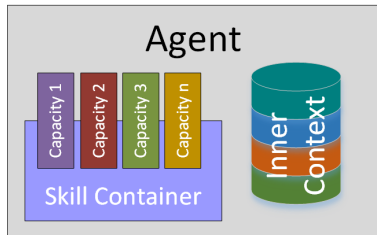
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A SARL Agent has inherently a set of **Built-in** Capacities

Current Built-in Capacities

- ExternalContextAccess
- InnerContextAccess
- Behaviors
- Lifecycle
- Schedules
- DefaultContextInteractions



Behaviors Built-in Capacity

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Motivation

Design Principles

Main Concepts

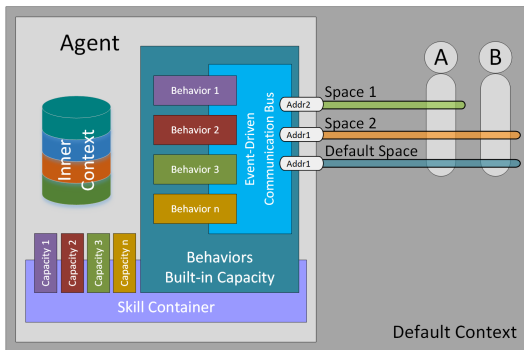
Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works



Behavior

Defines the actions to be performed on a given perception (Events) in a Space.



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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

Dimensions of the Environment

- Execution
- Physic
- Social

Key Ideas

- It is omnipresent
- Agents can interact with it via Capacities and Spaces
- Manages access to resources and structures



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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works

Execution Environment requirements

- Handles Agent's Lifecycle
- Provides Built-in Capacities
- Implements SARL concepts
- Handles resources

Janus as SARL Execution Environment

- Fully distributed.
- Dynamic discovery of Kernels.
- Automatic synchronization of kernels' data (easy recovery).
- Micro-Kernel implementation.



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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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Physical Environment

Class of real or simulated systems in which agents and objects have an explicit position, and that produce localized actions.

Properties

- Contains all objects
- Agents interact with it via dedicated Capacities
- Agents' Bodies are “managed” by the Environment
- Multiple “Views” of the environment can be implemented (1D, 2D, 3D)
- Enforces Universal Laws (e.g. Laws of physics)

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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Social Dimension

- Multiple ways of agent interaction
- Supported by Space / SpaceSpecification
- Default Interaction Space: based on events (may be redefined).
- Programmer can create new SpaceSpecifications (and ways of interacting):
 - FIPA
 - Organizational (MOISE, CRIO, etc)
- Social Dimension may influence other dimensions



Integration of the Environment Dimensions

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

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- Enables “communication” between dimensions
 - Constrains of actions/interactions from other dimensions
 - Different perceptions of the same Event according to the dimension
 - Interactions / Perceptions due to interactions in other dimensions
- Seen as Monolithic by Agent accessed by dedicated Capacities and Spaces (Holonc view)
- Should provide a uniform interface of the environment (Simulation vs Real World)



Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works

1 GITIA - UTN

2 SARL Team

3 Motivation

4 Design Principles

5 Main Concepts

- Definitions
- Built-in Capacities
- Environment

6 Show me the Code!

7 Summary & Future works



Show me the Code!

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SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

Demo



Outline

GITIA - UTN

SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works



- 1 GITIA - UTN
- 2 SARL Team
- 3 Motivation
- 4 Design Principles
- 5 Main Concepts
 - Definitions
 - Built-in Capacities
 - Environment
- 6 Show me the Code!
- 7 Summary & Future works

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SARL Team

Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the
Code!

Summary &
Future works

What does SARL currently provide ?

- Defines general agent-technology concepts: Context, Space, Agent, Capacity, Skill.
- All agents are holons.
- Intuitive Syntax (and the associated Eclipse-based IDE).
- Extensible (Capacities and Skill)
- No single way of interacting imposed.
- Janus as SARL platform



Agent Architectures:

- Capacities for **Reasoning Agent**: knowledge, plans, goals definition, multiple “reasoning engines”, etc.

Environments:

- Define the organizational extensions firstly based on CRIO then MOISE ☺: static and dynamic (normative).
- Continue work on physical environment integration, and its interaction with the other dimensions.

Language:

- Enforcing Pre- and post-conditions.
- Formal specification.
- Define grammar extensions for describing the environments instances.



Join Us

The whole is greater than the sum of its parts

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Motivation

Design Principles

Main Concepts

Definitions

Built-in Capacities

Environment

Show me the Code!

Summary & Future works

Join Us

- Open Source Project - Apache v2 License
- SARL
 - <http://www.sarl.io>
 - <http://www.github.com/sarl>
- Janus Project
 - <http://www.janusproject.io>
 - <http://www.github.com/janus-project>
- Every contributor is welcome 😊





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Environment
Models

Bibliography

8 Environment Models

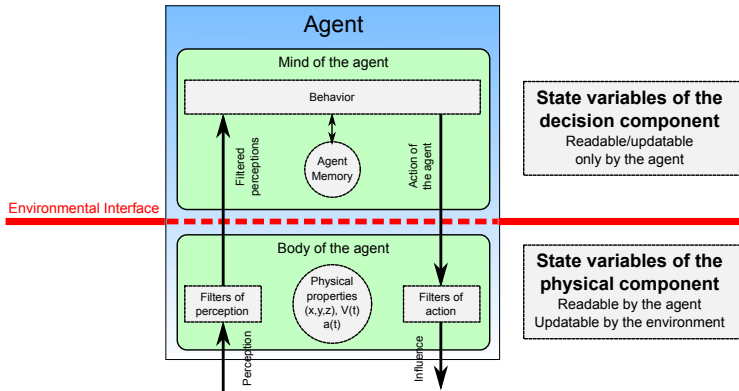
9 Bibliography



Body-mind separation

Environment
Models

Bibliography



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Environment
Models

Bibliography

8 Environment Models

9 Bibliography



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Environment
Models

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